DESIGN OF MACHINE ELEMENTS

Module-II

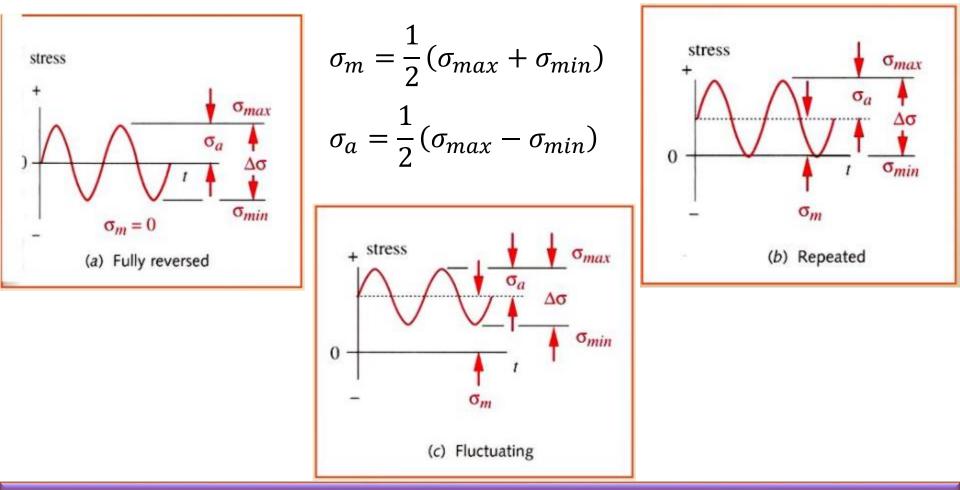
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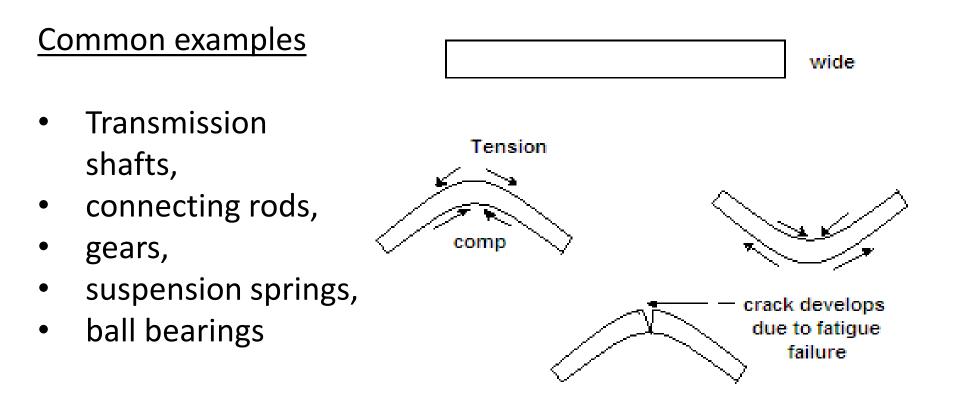
Fluctuating Stresses

Stress that arise due to the variation in magnitude of force with respect to time



Fatigue Failure

Failure < Ultimate tensile strength of the material Time delayed fracture under cyclic loading: Fatigue failure



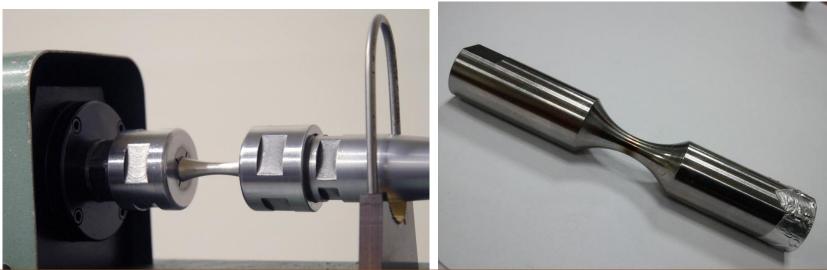
Fatigue Failure Regions



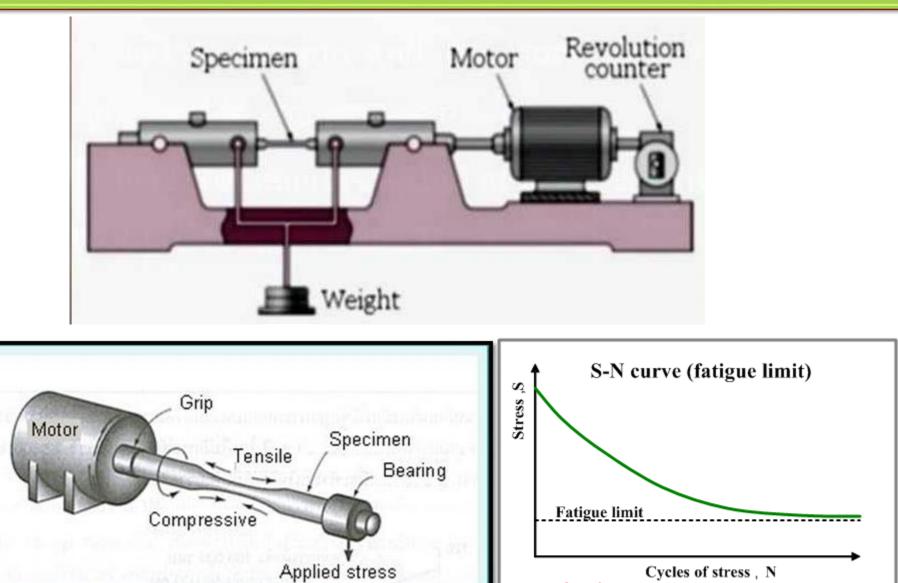
Endurance limit

Endurance limit is the maximum amplitude of <u>completely</u> <u>reversed stress</u> that the standard specimen can sustain for an <u>unlimited number of cycles</u> without fatigue failure

Fatigue life is defined as the <u>number of stress cycles</u> that the standard specimen can complete during the test <u>before the appearance</u> of the first fatigue crack

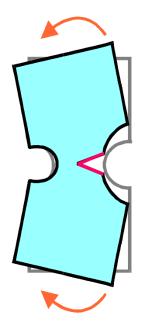


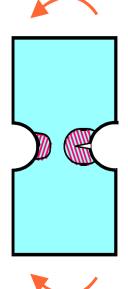
Fatigue Testing



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Low Cycle and High Cycle Fatigue





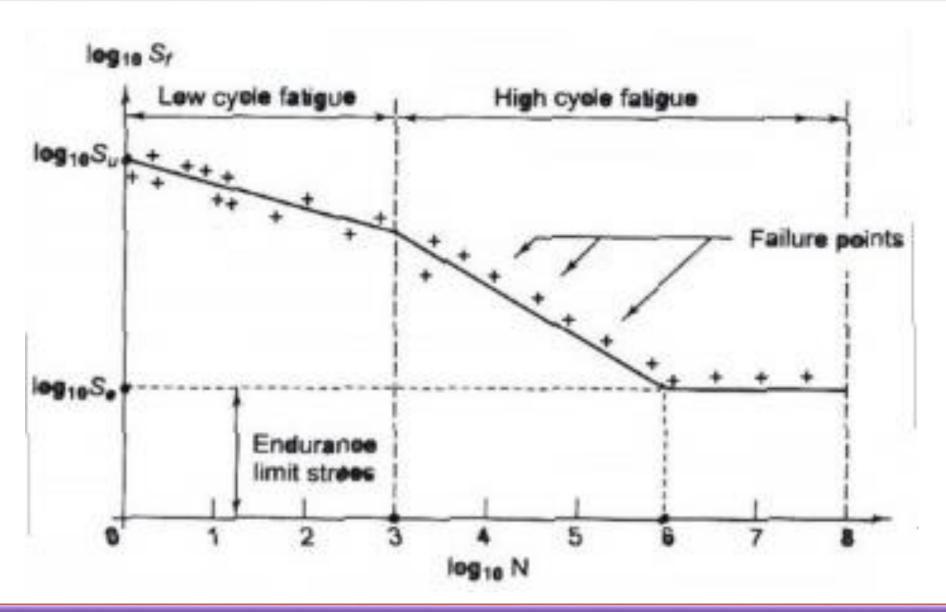
Static failure (large global deformation and large plastic strain) Low cycle fatigue (small local plastic strains) High cycle fatigue (small local elastic strains)

0 cycle

0-10³ cycles

10³ -10⁸ cycles

Low Cycle and High Cycle Fatigue



Notch Sensitivity

$$K_{tf} = \frac{Endurance \ limit \ of \ the \ notch \ free \ specimen}{Endurance \ limit \ of \ the \ notched \ specimen}$$

Eqn 2.12(a)

Notch sensitivity is defined as the susceptibility of a material to succumb to the damaging effects of stress raising notches in fatigue loading.

 $q = \frac{Increase \ of \ actual \ stress \ over \ nominal \ stress}{Increase \ of \ theoretical \ stress \ over \ nominal \ stress}$

$$q = \frac{(K_{tf}\sigma_o - \sigma_o)}{(K_t\sigma_o - \sigma_o)}$$

$$K_{tf} = 1 + q(K_t - 1)$$

Eqn 2.4

Endurance limit: Estimation

$$S_e = K_a K_b K_c K_d S'_e$$

- S_e: endurance limit of a particular mechanical component subjected to reversed bending stress
- S'_e: endurance limit stress of a rotating beam specimen subjected to reversed bending stress
- K_a : Surface finish factor
- *K_b*: Size factor
- *K_c*: Reliability factor
- K_d : Modifying factor accounting stress concentration factor

Surface finish factor (K_a)

- *K_a*: To account for the stress raisers due to the poor surface finish
- They are derating factors
- $K_a = a(S_{ut})^b$ (shigley and Mischke)

Coefficient values for steel

Surface finish	а	b
Ground	1.58	-0.085
Machined or cold drawn	4.51	-0.265
Hot-rolled	57.7	-0.718
As forged	272	-0.995

Size factor (K_b)

- K_b : To account for the increase in size
- For 2.79 mm $\leq d \leq$ 51 mm
 - $K_b = 1.24(d)^{-0.107}$ (shigley and Mischke)
- For 51 mm \leq d \leq 254mm
 - $K_b = 0.859 0.000873d$

Values of size factor

Diameter (d) mm	K _b
$d \leq 7.5$	1
$7.5 \le d \le 50$	0.85
d > 50	0.75

Reliability Factor (K_c)

- K_c : To account for the dispersion of data obtained from the experimental tests
- Standard deviation of test is 8% of mean value
- K_c =1, Reliability =50%

Reliability factor

Reliability R (%)	K _c	
50	1.000	
90	0.897	
95	0.868	
99	0.814	
99.9	0.753	
99.99	0.702	

Modifyng Factor accounting stress concentration (K_d)

- K_d : To account for the stress concentration
- $K_d = \frac{1}{K_f}$

Axial loading to rotating beam bending $(S_e)_a = 0.8 S_e$

Design for finite and infinite life (Fully reversed cycle)

Case 1: Design for infinite life

Endurance limit becomes the failure criterion

$$\sigma_a = \frac{S_e}{fs} \qquad \qquad \tau_a = \frac{S_{se}}{fs}$$

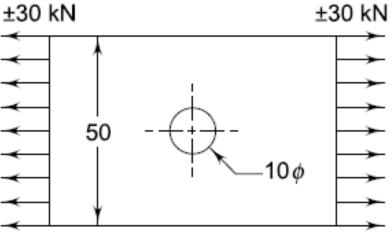
Case 2: Design for finite life

A straight line AB drawn from (0.9 S_{ut}) at 10³ cycle to (S_e) at 10⁶ cycles on a log-log paper

- Locate point A and B
- Join AB
- Depending on life N obtain S_f

Problem 2.1

A plate made of steel 20C8 (S_{ut} =440 N/mm²) is hot rolled and normalised condition is shown in Figure. It is subjected to a completely reversed axial load of 30 kN. The notch sensitivity factor q can be taken as 0.8 and the expected reliability is 90%. The size facto is 0.85. The factor of safety is 2. Determine the plate thickness for infinite life

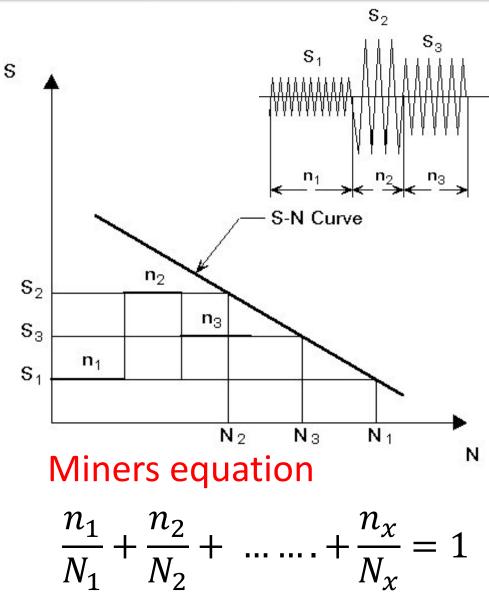


Cumulative damage in fatigue

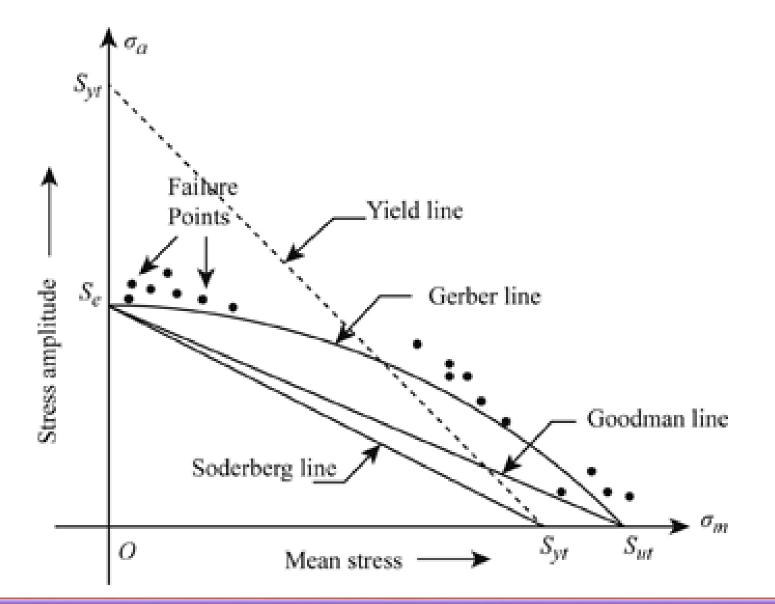
First set of cycle = n_1 Stress in the first cycle = S_1 Fatigue life with n_1 cycle = N_1

Second set of cycle = n_2 Stress in the second cycle = S_2 Fatigue life with n_2 cycle = N_2

 x^{th} set of cycle = n_x Stress in the x^{th} set = S_x Fatigue life with n_x cycle = N_x



Soderberg, Goodman and Gerber line



<u>Gerber line</u>: A parabolic curve joining S_e on the ordinate to S_{ut} on the abscissa

$$\frac{S_a}{S_e} + \left(\frac{S_m}{S_{ut}}\right)^2 = 1$$

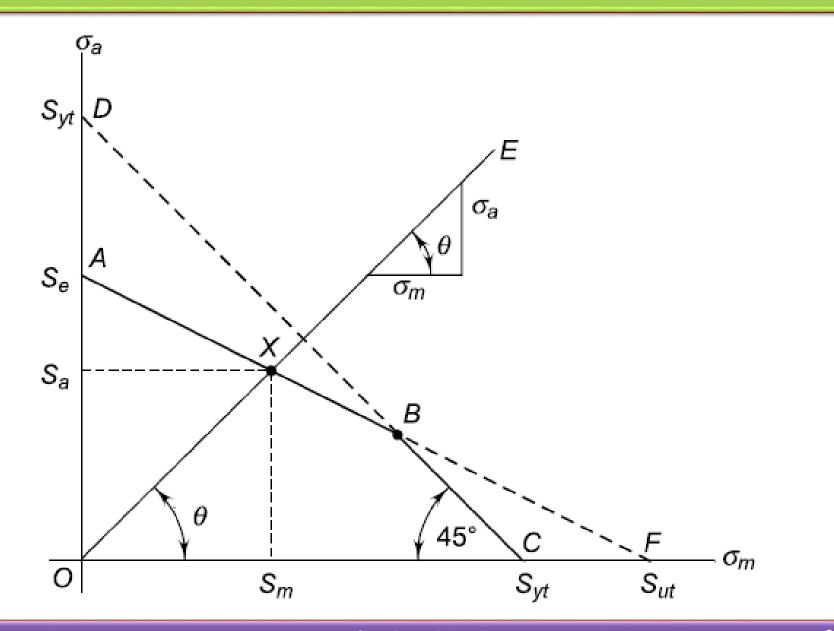
Soderberg line: A straight line joining S_e on the ordinate to S_{yt} on the abscissa

$$\frac{S_m}{S_{yt}} + \frac{S_a}{S_e} = 1$$

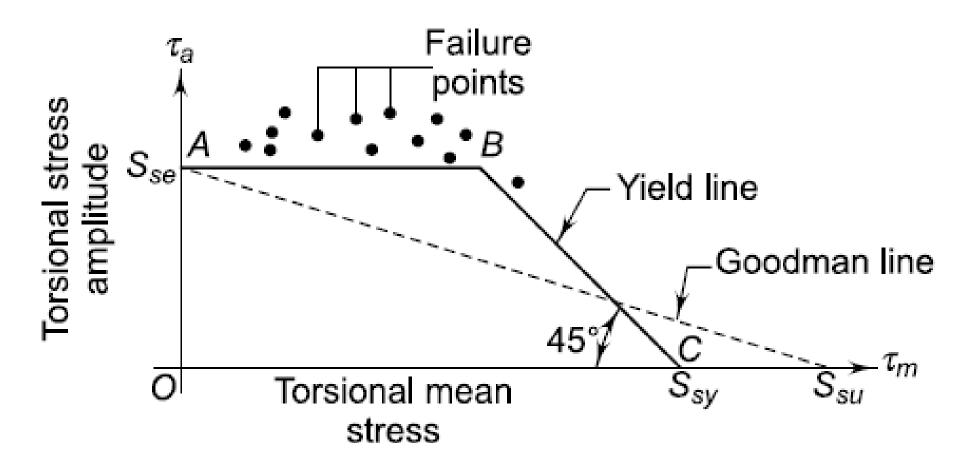
Goodman line: A straight line joining S_e on the ordinate to S_{ut} on the abscissa

$$\frac{S_m}{S_{ut}} + \frac{S_a}{S_e} = 1$$

Modified Goodman Diagrams: Pure Bending or Tensile



Modified Goodman Diagrams: Pure Torsional Load



Fatigue Design Under Combined Loading

Most general equation of distortion energy theory

$$\sigma^{2} = \frac{1}{2} \left[\left(\left(\sigma_{x} - \sigma_{y} \right)^{2} + \left(\sigma_{y} - \sigma_{z} \right)^{2} + \left(\sigma_{z} - \sigma_{x} \right)^{2} + 6 \left(\tau_{xy}^{2} + \tau_{yz}^{2} + \tau_{zx}^{2} \right) \right) \right]$$

For a 2D normal stress case

$$\sigma_m = \sqrt{\left(\sigma_{xm}^2 - \sigma_{xm}\sigma_{ym} + \sigma_{ym}^2\right)}$$
$$\sigma_a = \sqrt{\left(\sigma_{xa}^2 - \sigma_{xa}\sigma_{ya} + \sigma_{ya}^2\right)}$$

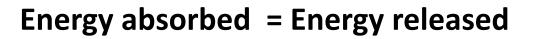
Combined bending and torsional case

$$\sigma_m = \sqrt{\left(\sigma_{xm}^2 + 3\tau_{xym}^2\right)}$$
$$\sigma_a = \sqrt{\left(\sigma_{xa}^2 + 3\tau_{xya}^2\right)}$$

Problem

A transmission shaft carries a pulley midway between the two bearings. The bending moment at the pulley varies from 200 N-m to 600 N-m, as the torsional moment in the shaft varies from 70 N-m to 200 N-m. The frequencies of variation of bending and torsional moments are equal to the shaft speed: The shaft is made of steel FeE400 (S_{ut} = 540 N/mm² and S_{vt} = 400 N/mm²). The corrected endurance limit of the shaft is 200 N/mm². Determine the diameter of the shaft using a factor of safety of 2.

- Defined as a collision of one component in motion with a second component, which may be either in motion or at rest
- Load which is applied rapidly to the machine component
 - Energy released (weight)= W(h+ δ)
 - Energy absorbed (load × Deflection)= $\frac{1}{2}P\delta$



$$\frac{P}{W} = \left[1 + \sqrt{1 + \frac{2hAE}{Wl}}\right]$$

W

h

Factor of safety

Reserve strength:

$$fs = \frac{failure\ stress}{allowable\ stress} = \frac{failure\ load}{working\ load}$$

• For ductile materials

•
$$fs = \frac{S_{yt}}{\sigma}$$

• For brittle materials

•
$$fs = \frac{S_{ut}}{\sigma}$$

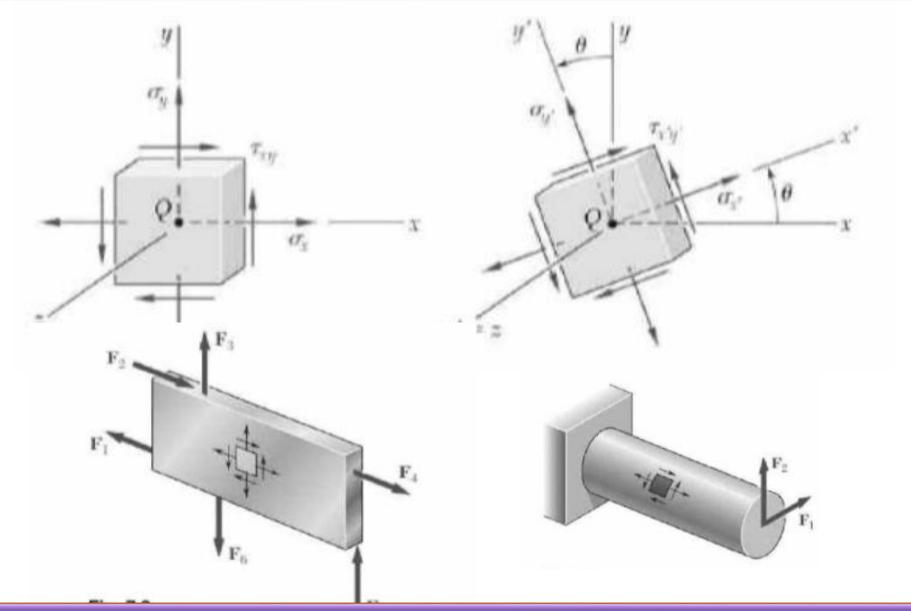
Reason for Factor of safety

- Uncertainty in magnitude of external force
- Variation in properties
- Variation in dimensions of the component
- Assumptions of material properties

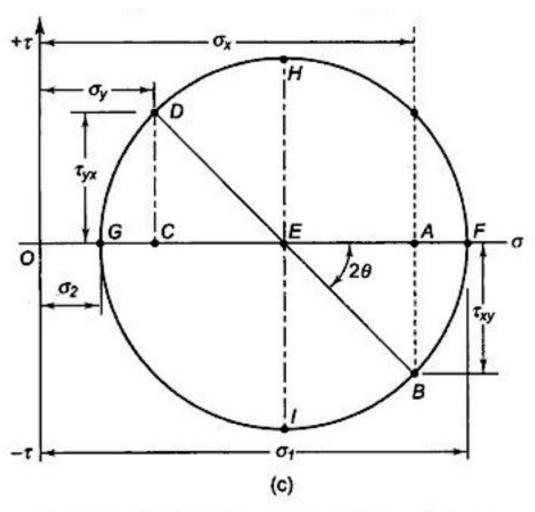
Factor of safety: Magnitude Selection

- Effect of failure
- Type of load
- Material of component
- Degree of accuracy in force analysis
- Reliability of the component
- Cost of the component
- Testing of machine element
- Service conditions
- Quality of manufacture

Stress state



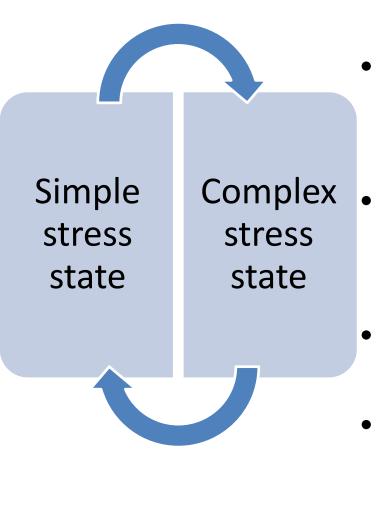
Mohr's Circle



Principal Stress Principal shear stress????

Fig. 4.30 (a) Two-Dimensional State of Stress (b) Stresses on Oblique Plane (c) Mohr's Circle Diagram

Theories of Elastic failure



- Maximum principal stress theory
 - (Rankine's theory)
- Maximum shear stress theory
 - (Coulumb, Tresca and Guest's theory)
 - Distortion energy theory
 - (Huber von mises and Hencky's theory)
- Maximum strain theory
 - (St. Venant's theory)
- Maximum total strain energy theory
 - (Haigh's theory)

Maximum principal stress theory (Rankine's theory)

The failure of mechanical component subjected to bi-axial or tri-axial stresses occurs when the maximum principal stress reaches the yield or ultimate strength of the material.

If,
$$\sigma_1 > \sigma_2 > \sigma_3$$

$$\sigma_1 = S_{yt}$$
 or $\sigma_1 = S_{ut}$

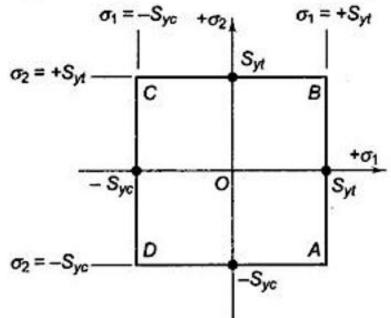


Fig. 4.31 Boundary for Maximum Principal Stress Theory under Bi-axial Stresses

Maximum shear stress theory (Guest's theory)

The failure of mechanical component subjected to bi-axial or tri-axial stresses occurs when the maximum shear stress at any point in the component becomes equal to the maximum shear stress in the standard specimen of the tension test, when yielding starts

$$\tau_{max} = \frac{\sigma_1}{2} = \frac{S_{yt}}{2}$$

Yield strength in shear is half of the yield strength in tension

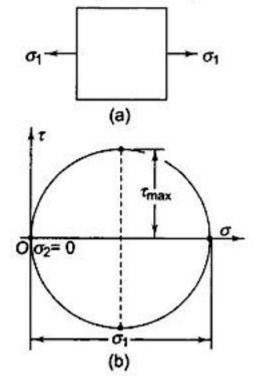
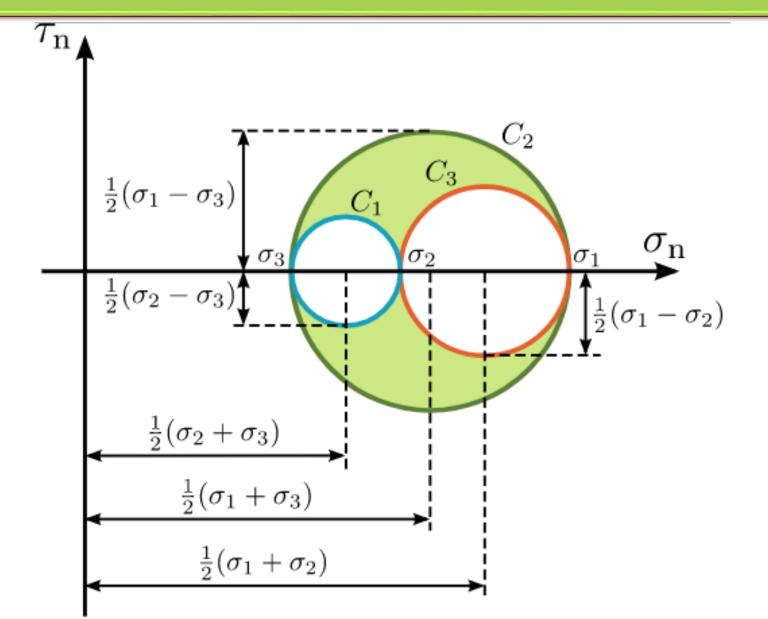


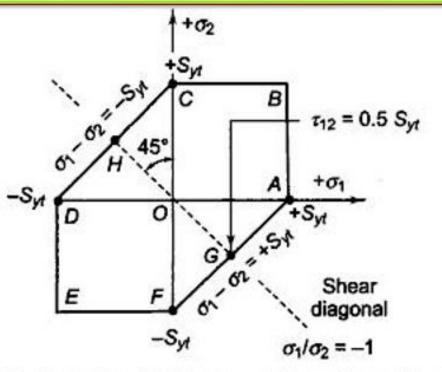
Fig. 4.32 (a) Stresses in Simple Tension Test (b) Mohr's Circle for Stresses

Mohr's diagram



Maximum shear stress theory (Guest's theory)

$$\tau_{12} = \frac{\sigma_1 - \sigma_2}{2} = \frac{S_{yt}}{2}$$
$$\tau_{23} = \frac{\sigma_2 - \sigma_3}{2} = \frac{S_{yt}}{2}$$
$$\tau_{31} = \frac{\sigma_3 - \sigma_1}{2} = \frac{S_{yt}}{2}$$



 $\sigma_{1} - \sigma_{2} = S_{yt}$ $\sigma_{2} - \sigma_{3} = S_{yt}$ $\sigma_{3} - \sigma_{1} = S_{yt}$

Fig. 4.33 Boundary for Maximum Shear Stress Theory under Bi-axial Stresses

$$\sigma_{1} - \sigma_{2} = \pm S_{yt}$$
$$\sigma_{2} = \pm S_{yt}$$
$$\sigma_{1} = \pm S_{yt}$$

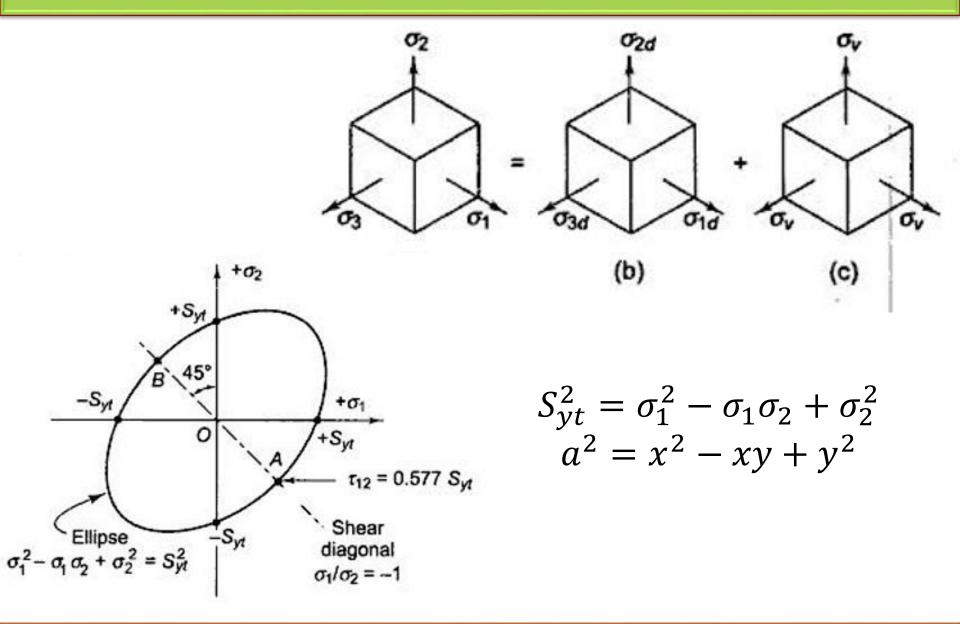
Distortion energy theory (Von Mises and Hencky's)

The theory states that the failure of mechanical component subjected to bi-axial and tri-axial stresses occurs when the strain energy of distortion per unit volume at any point in the component, becomes equal to the strain energy of distortion per unit volume in the standard specimen of tension-test, when yielding starts.

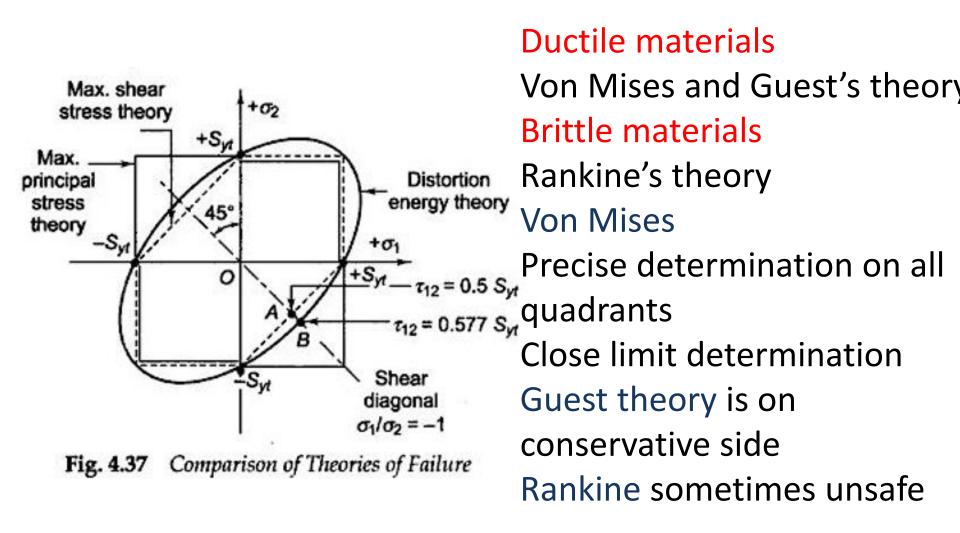
Total strain energy of the cube, U

$$U = \frac{1}{2}\sigma_{1}\epsilon_{1} + \frac{1}{2}\sigma_{2}\epsilon_{2} + \frac{1}{2}\sigma_{3}\epsilon_{3}$$
$$U = \frac{1}{2E} \left[(\sigma_{1}^{2} + \sigma_{2}^{2} + \sigma_{3}^{2}) - 2\mu(\sigma_{1}\sigma_{2} + \sigma_{2}\sigma_{3} + \sigma_{3}\sigma_{1}) \right]$$

Distortion energy theory (Von Mises and Hencky's)



Comparison



The theory states that failure or yielding occurs at point in a member when maximum principal (or normal) strain in a biaxial or tri-axial stress system reaches the limiting value of strain as determined from simple tension test

$$\varepsilon_{max} = \frac{\sigma_1}{E} - \mu \frac{\sigma_2}{E} \qquad \qquad \varepsilon_{max} = \frac{S_{yt}}{E}$$
$$S_{yt} = \sigma_1 - \mu \sigma_2$$

*Not commonly used

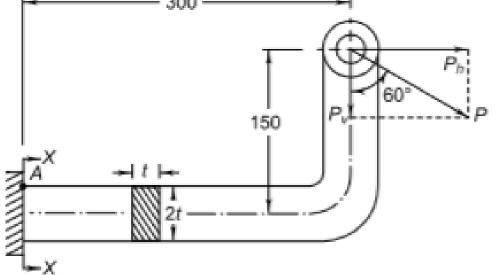
The theory states that failure or yielding occurs at point in a member when the strain energy per unit volume in a bi-axial or tri-axial stress system reaches the limiting strain energy as determined from simple tension test

$$U_1 = \frac{1}{2E} \left[(\sigma_1)^2 + (\sigma_2)^2 - 2\mu\sigma_1\sigma_2 \right] \qquad \qquad U_2 = \frac{1}{2E} S_{yt}^2$$

$$(\sigma_1)^2 + (\sigma_2)^2 - 2\mu\sigma_1\sigma_2 = S_{yt}^2$$

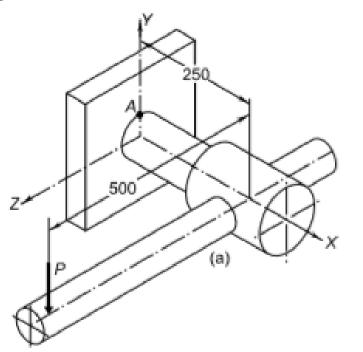
Problem 2.2

A wall bracket with a rectangular cross section is shown in Figure. The depth of the cross section is twice of the width. The force P acting on the bracket at 60° to the vertical is 5 kN. The material of the bracket is grey cast iron FG 200 and the factor of safety is 3.5. Determine the dimensions of the cross-section of the bracket. Assume maximum normal stress theory.



Problem 2.3

The shaft of an overhang crank subjected to a force P of 1 kN is shown in Figure. The shaft is made of plain carbon steel 45C8 and the tensile yield strength is 380 N/mm². The factor of safety is 2. Determine the diameter of the shaft using the maximum shear stress theory.

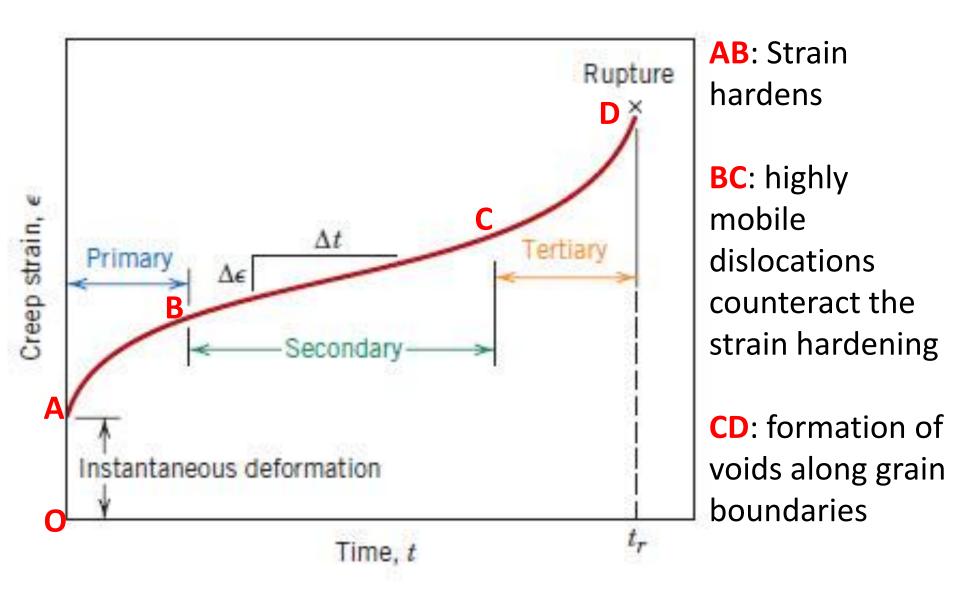


<u>Creep Strength</u> of the material is defined as the

maximum stress that the material can withstand for a specified length of time without excessive deformation

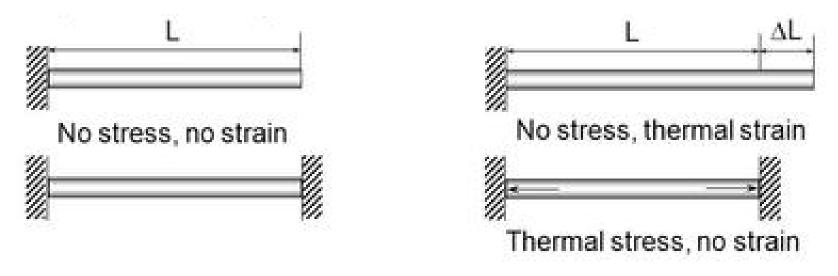
<u>Creep rupture strength</u> of the material is the maximum stress that the material can withstand for a specified length of time without rupture

Creep



Thermal Stresses

Stress that arise due to the variation in temperature



For a rod, $\sigma = -\alpha E \Delta T$ For a plate (2D) $\sigma_x = \sigma_y = \frac{-\alpha E \Delta T}{1 - \mu}$ For a box (3D) $\sigma_x = \sigma_y = \sigma_z = \frac{-\alpha E \Delta T}{1 - 2\mu}$